

# On stability for the Ekman boundary layer

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We present a result on well-posedness and stability for the Ekman boundary layer problem in the space  $\text{FM}(\mathbb{R}^2, L^2(\mathbb{R}_+))$ , i.e., in the space of  $L^2(\mathbb{R}_+)$ -valued Fourier transformed Radon measures. We obtain stability in all appearing parameters as time, angle velocity of rotation, viscosity, and layer thickness.

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## 1 Description and main result

The Ekman boundary layer problem is a meteorological model for the motion of a rotating fluid (atmosphere) inside a boundary layer, appearing in between a uniform geostrophic flow (wind) and a solid boundary (earth) at which the no slip condition applies. Mathematically this situation is described by the Navier-Stokes equations with Coriolis force

$$\begin{cases} \partial_t u - \nu \Delta u + (u, \nabla)u + 2\Omega e_3 \times u = -\nabla p & \text{in } \mathbb{R}_+^3 \times (0, T), \\ \operatorname{div} u = 0 & \text{in } \mathbb{R}_+^3 \times (0, T), \\ u = 0 & \text{on } \partial\mathbb{R}_+^3 \times (0, T), \\ u|_{t=0} = u_0 & \text{in } \mathbb{R}_+^3. \end{cases} \quad (1)$$

Here the unknowns  $u$  and  $p$  denote velocity and pressure of the fluid respectively, whereas  $e_3 = (0, 0, 1)$  and the parameters  $\nu$  and  $\Omega$  correspond to viscosity and angle velocity of the rotation around the  $x_3$ -axis.

There is a famous stationary exact solution to (1) called Ekman spiral and which is given by the vector

$$\mathbf{U}^E(x_3) = U_\infty \left( 1 - e^{-x_3/\delta} \cos(x_3/\delta), e^{-x_3/\delta} \sin(x_3/\delta), 0 \right)$$

Here  $\delta = \sqrt{\nu/\Omega}$  denotes the layer thickness and  $U_\infty$  the velocity of the geostrophic flow away from the boundary which is pointing in  $x_1$  direction. The corresponding pressure to  $\mathbf{U}^E$  is given by  $p^E(x_2) = -\Omega U_\infty x_2$ . Remarkable persistent stability of the Ekman spiral in atmospheric and oceanic boundary layers has been noticed in geophysical literature. We are interested in stability results in the parameters  $t, \Omega, \nu$ , and  $\delta$ . In particular in the existence of solutions with norms uniformly bounded in  $\Omega$  in spaces including functions nondecaying at infinity. Results of this type are essential in studies of statistical properties of turbulence, see e.g. [6, 7], and in the analysis of fast oscillating singular limits for system (1), see e.g. [5].

The observation that  $\mathbf{U}^E$  depends on the  $x_3$  variable only, i.e., it has infinite energy, and that

$$\lim_{x_3 \rightarrow \infty} \mathbf{U}^E(x_3) \rightarrow (U_\infty, 0, 0)$$

leads to two natural requirements on a potential class  $\mathbb{E}$  of initial data:

(i) The class  $\mathbb{E}$  should include functions nondecreasing at infinity in tangential direction.

(ii)  $u_0 \rightarrow (U_\infty, 0, 0)$  if  $x_3 \rightarrow \infty$  in a certain sense.

A first result on well-posedness for system (1) is obtained in [4] for  $u_0$  in the class

$$\mathbb{E} = \left\{ u \in \dot{B}_{\infty,1}^0(\mathbb{R}^2, L^p(\mathbb{R}_+)^3) + \mathbf{U}^E : \operatorname{div} u = 0, u^3|_{\partial\mathbb{R}_+^3} = 0 \right\}, \quad p > 2.$$

Here  $\dot{B}_{\infty,1}^0(\mathbb{R}^2, L^p(\mathbb{R}_+)^3)$  stands for the  $L^p(\mathbb{R}_+)^3$ -valued version of the standard homogeneous Besov space  $\dot{B}_{\infty,1}^0(\mathbb{R}^2, \mathbb{C})$ . Note that the space  $\dot{B}_{\infty,1}^0(\mathbb{R}^2, L^p(\mathbb{R}_+)^3)$  contains  $L^p(\mathbb{R}_+)^3$ -valued almost periodic functions. Thus,  $\mathbb{E}$  satisfies (i) and (ii).

However, it seems that this class is inappropriate for stability investigations. This relies essentially on the fact that the Poincaré-Riesz semigroup  $(e^{-tB\Omega})_{t \geq 0}$  generated by the Coriolis operator  $B_\Omega u := 2\Omega e_3 \times u$  proved to be unbounded in  $t$  and

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$\Omega$  in the space  $L^p(\mathbb{R}^3)$ , unless  $p = 2$ . The uniform boundedness in  $L^2$  is a consequence of the fact that here a multiplier result as

$$\|\mathcal{F}^{-1}m\mathcal{F}\|_{\mathcal{L}(L^2(\mathbb{R}^3)^3)} \leq \|m\|_{L^\infty(\mathbb{R}^3)^{3 \times 3}} \quad (2)$$

for bounded  $m : \mathbb{R}^3 \rightarrow \mathbb{C}^3$  is available by virtue of Placherel's theorem and since the symbol of the Poincaré-Riesz is bounded (and uniformly bounded in  $t$  and  $\Omega$ ). Here  $\mathcal{L}(X)$  denotes the class of all bounded operators on a Banach space  $X$ , and  $\mathcal{F}$  and  $\mathcal{F}^{-1}$  the Fourier transform and its inverse respectively. Hence, in order to obtain results on stability, besides the natural requirements (i) and (ii), a potential class of initial data should also admit a multiplier result as (2). A suitable class satisfying these requirements and which is still large enough is the class

$$\mathbb{E} = \text{FM}_{0,\sigma}(\mathbb{R}^2, L^2(\mathbb{R}_+)) + \mathbf{U}^E,$$

where

$$\text{FM}_{0,\sigma}(\mathbb{R}^2, L^2(\mathbb{R}_+)) = \left\{ \mathcal{F}u : u \in \text{M}(\mathbb{R}^2, L^2(\mathbb{R}_+)^3), |u|(\{0\}) = 0, \text{div } \mathcal{F}u = 0, \mathcal{F}u^3|_{\partial\mathbb{R}_+^3} = 0 \right\}$$

equipped with the norm  $\|\mathcal{F}u\|_{\text{FM}(X)} := \|u\|_{\text{M}(X)} := |u|(\mathbb{R}^3)$ . Here  $\text{M}(\mathbb{R}^3, X)$  denotes the space of finite  $X$ -valued Radon measures and  $|u|(\mathcal{O}) := \sup \left\{ \sum_{A \in \Pi} \|u(A)\|_X : \Pi \text{ finite partition of } \mathcal{O} \right\}$  the total variation measure of an open set  $\mathcal{O} \subseteq \mathbb{R}^2$ . Typical examples important for our purposes and included in the space  $\text{FM}_{0,\sigma}(\mathbb{R}^2, L^2(\mathbb{R}_+))$  are given by almost periodic functions as

$$u_0(x) := \sum_{j=1}^{\infty} a_j e^{i\lambda_j \cdot x}, \quad x \in \mathbb{R}^2, \lambda_j \neq 0, a_j \in L^2(\mathbb{R}_+)^3, \sum_{j=1}^{\infty} \|a_j\|_2 < \infty.$$

The significance of the space  $\text{FM}_{0,\sigma}(\mathbb{R}^3, \mathbb{C})$  for the Navier-Stokes equations with rotation in the whole space  $\mathbb{R}^3$  was already pointed out in [2] and [3]. In [2] a local-in-time existence result is proved with an existence interval independent of  $\Omega$ . In [3] global-in-time solvability and exponential stability is derived for initial data  $u_0 \in \text{FM}_{0,\sigma}(\mathbb{R}^3, \mathbb{C})$  such that  $\text{supp } \mathcal{F}u_0$  is contained in a sum-closed frequency set. Moreover, the required smallness condition is explicitly given in terms of the Reynolds number and all the results are independent of  $\Omega$ . Consequently, we have stability in all appearing parameters.

Adopting the ideas from [2] and [3] we can prove a corresponding result for the Ekman boundary layer problem, i.e., for system (1). Our main result reads as follows.

**Theorem 1.1** *Let  $\nu, \delta > 0$  and  $\Omega \in \mathbb{R}$ . For each  $u_0 \in \text{FM}_{0,\sigma}(\mathbb{R}^2, L^2(\mathbb{R}_+)) + \mathbf{U}^E$  there exists a  $T_0 \geq C \|u_0\|_{\text{FM}(L^2)}^2$  with  $C > 0$  independent of  $\Omega$  and a unique classical solution  $u \in C([0, T_0], \text{FM}_{0,\sigma}(\mathbb{R}^2, L^2(\mathbb{R}_+)) + \mathbf{U}^E)$  of system (1).*

The proof is based on a generator result independent of  $\Omega$  for the linearized Stokes equations (system (1) without the term  $(u, \nabla)u$ ). The essential ingredient in deriving the generator result, in turn, is a multiplier result on the space of Fourier transformed Radon measures  $\text{FM}_{0,\sigma}(\mathbb{R}^2, L^2(\mathbb{R}_+))$  corresponding to (2). More precisely, we can prove the estimate

$$\|\mathcal{F}^{-1}m\mathcal{F}\|_{\mathcal{L}(\text{FM}_{0,\sigma}(\mathbb{R}^2, L^2(\mathbb{R}_+)))} \leq \|m\|_{L^\infty(\mathbb{R}^2, \mathcal{L}(L^2(\mathbb{R}_+)))^{3 \times 3}}$$

for  $m \in [C(\mathbb{R}^2 \setminus \{0\}, \mathcal{L}(L^2(\mathbb{R}_+))) \cap L^\infty(\mathbb{R}^2, \mathcal{L}(L^2(\mathbb{R}_+)))]^{3 \times 3}$ . The contraction mapping principle applied on the mild formulation of (1) then yields Theorem 1.1.

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